

AD8091/AD8092

FEATURES

- Low-Cost Single (AD8091), Dual (AD8092)**
- Voltage Feedback Architecture**
- Fully Specified at +3 V, +5 V, and ± 5 V Supplies**
- Single-Supply Operation**
 - Output Swings to within 25 mV of Either Rail**
 - Input Voltage Range**
 - 0.2 V to +4 V; $V_S = +5$ V
- High-Speed and Fast Settling on +5 V**
 - 110 MHz -3 dB Bandwidth ($G = +1$)
 - 145 V/ μ s Slew Rate
 - 50 ns Settling Time to 0.1%
- Good Video Specifications ($G = +2$)**
 - Gain Flatness of 0.1 dB to 20 MHz; $R_L = 150 \Omega$
 - 0.03% Differential Gain Error; $R_L = 1 \text{ k}\Omega$
 - 0.03° Differential Phase Error; $R_L = 1 \text{ k}\Omega$
- Low Distortion**
 - 80 dBc Total Harmonic @ 1 MHz; $R_L = 100 \Omega$
- Outstanding Load Drive Capability**
 - Drives 45 mA, 0.5 V from Supply Rails
 - Drives 50 pF Capacitive Load ($G = +1$)
- Low Power of 4.4 mA/Amplifier**

APPLICATIONS

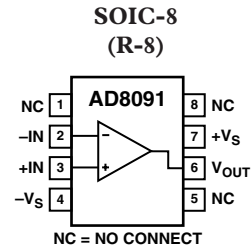
- Coaxial Cable Driver
- Active Filters
- Video Switchers
- Professional Cameras
- CCD Imaging Systems
- CD/DVD

PRODUCT DESCRIPTION

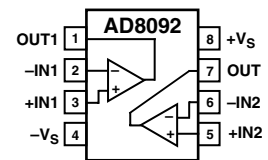
The AD8091 (single) and AD8092 (dual) are low-cost, voltage feedback, high-speed amplifiers designed to operate on +3 V, +5 V, or ± 5 V supplies. They have true single-supply capability with an input voltage range extending 200 mV below the negative rail and within 1 V of the positive rail.

Despite their low cost, the AD8091/AD8092 provide excellent overall performance and versatility. The output voltage swing extends to within 25 mV of each rail, providing the maximum output dynamic range with excellent overdrive recovery. This makes the AD8091/AD8092 useful for video electronics, such as cameras, video switchers, or any high-speed portable equipment. Low distortion and fast settling make them ideal for active filter applications.

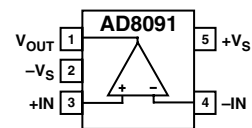
CONNECTION DIAGRAMS



**μ SOIC-8 and SOIC-8
(RM-8, R-8)**



**SOT23-5
(RT-5)**



The AD8091/AD8092 offer a low-power supply current and can operate on a single +3 V power supply. These features are ideally suited for portable and battery-powered applications where size and power are critical.

The wide bandwidth and fast slew rate make these amplifiers useful in many general-purpose, high-speed applications where dual power supplies of up to ± 6 V and single supplies from +3 V to +12 V are needed.

All of this low-cost performance is offered in an 8-lead SOIC (AD8091/AD8092), along with a tiny SOT23-5 package (AD8091) and a μ SOIC package (AD8092).

REV. A

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AD8091/AD8092—SPECIFICATIONS (@ $T_A = 25^\circ\text{C}$, $V_S = +5\text{ V}$, $R_L = 2\text{ k}\Omega$ to $+2.5\text{ V}$, unless otherwise noted.)

| Parameter | Conditions | AD8091A/AD8092A | | | Unit |
|-------------------------------------|--|-----------------|----------------|------|------------------------------|
| | | Min | Typ | Max | |
| DYNAMIC PERFORMANCE | | | | | |
| -3 dB Small Signal Bandwidth | $G = +1$, $V_O = 0.2\text{ V p-p}$ | 70 | 110 | | MHz |
| Bandwidth for 0.1 dB Flatness | $G = -1, +2$, $V_O = 0.2\text{ V p-p}$ | | 50 | | MHz |
| Slew Rate | $G = +2$, $V_O = 0.2\text{ V p-p}$, $R_L = 150\ \Omega$ to $+2.5\text{ V}$, $R_F = 806\ \Omega$ | | 20 | | MHz |
| Full Power Response | $G = -1$, $V_O = 2\text{ V Step}$ | 100 | 145 | | V/ μs |
| Settling Time to 0.1% | $G = +1$, $V_O = 2\text{ V p-p}$ | | 35 | | MHz |
| | $G = -1$, $V_O = 2\text{ V Step}$ | | 50 | | ns |
| NOISE/DISTORTION PERFORMANCE | | | | | |
| Total Harmonic Distortion* | $f_C = 5\text{ MHz}$, $V_O = 2\text{ V p-p}$, $G = +2$ | | -67 | | dB |
| Input Voltage Noise | $f = 10\text{ kHz}$ | | 16 | | nV/ $\sqrt{\text{Hz}}$ |
| Input Current Noise | $f = 10\text{ kHz}$ | | 850 | | fA/ $\sqrt{\text{Hz}}$ |
| Differential Gain Error (NTSC) | $G = +2$, $R_L = 150\ \Omega$ to $+2.5\text{ V}$ | | 0.09 | | % |
| | $R_L = 1\text{ k}\Omega$ to $+2.5\text{ V}$ | | 0.03 | | % |
| Differential Phase Error (NTSC) | $G = +2$, $R_L = 150\ \Omega$ to $+2.5\text{ V}$ | | 0.19 | | Degrees |
| | $R_L = 1\text{ k}\Omega$ to $+2.5\text{ V}$ | | 0.03 | | Degrees |
| Crosstalk | $f = 5\text{ MHz}$, $G = +2$ | | -60 | | dB |
| DC PERFORMANCE | | | | | |
| Input Offset Voltage | T_{MIN} to T_{MAX} | | 1.7 | 10 | mV |
| Offset Drift | | | 10 | 25 | mV |
| Input Bias Current | T_{MIN} to T_{MAX} | | 1.4 | 2.5 | $\mu\text{A}/^\circ\text{C}$ |
| Input Offset Current | | | 0.1 | 0.75 | μA |
| Open-Loop Gain | $R_L = 2\text{ k}\Omega$ to $+2.5\text{ V}$ | 86 | 98 | | dB |
| | T_{MIN} to T_{MAX} | | 96 | | dB |
| | $R_L = 150\ \Omega$ to $+2.5\text{ V}$ | 76 | 82 | | dB |
| | T_{MIN} to T_{MAX} | | 78 | | dB |
| INPUT CHARACTERISTICS | | | | | |
| Input Resistance | | | 290 | | k Ω |
| Input Capacitance | | | 1.4 | | pF |
| Input Common-Mode Voltage Range | | | -0.2 to +4 | | V |
| Common-Mode Rejection Ratio | $V_{\text{CM}} = 0\text{ V}$ to $+3.5\text{ V}$ | 72 | 88 | | dB |
| OUTPUT CHARACTERISTICS | | | | | |
| Output Voltage Swing | $R_L = 10\text{ k}\Omega$ to $+2.5\text{ V}$ | | 0.015 to 4.985 | | V |
| | $R_L = 2\text{ k}\Omega$ to $+2.5\text{ V}$ | 0.100 to 4.900 | 0.025 to 4.975 | | V |
| | $R_L = 150\ \Omega$ to $+2.5\text{ V}$ | 0.300 to 4.625 | 0.200 to 4.800 | | V |
| Output Current | $V_{\text{OUT}} = +0.5\text{ V}$ to $+4.5\text{ V}$ | | 45 | | mA |
| | T_{MIN} to T_{MAX} | | 45 | | mA |
| Short Circuit Current | Sourcing | | 80 | | mA |
| | Sinking | | 130 | | mA |
| Capacitive Load Drive | $G = +1$ | | 50 | | pF |
| POWER SUPPLY | | | | | |
| Operating Range | | 3 | | 12 | V |
| Quiescent Current/Amplifier | | | 4.4 | 5 | mA |
| Power Supply Rejection Ratio | $\Delta V_S = \pm 1\text{ V}$ | 70 | 80 | | dB |
| OPERATING TEMPERATURE RANGE | | | | | |
| | | -40 | | +85 | $^\circ\text{C}$ |

*Refer to TPC 7.

Specifications subject to change without notice.

SPECIFICATIONS (@ $T_A = 25^\circ\text{C}$, $V_S = +3\text{ V}$, $R_L = 2\text{ k}\Omega$ to $+1.5\text{ V}$, unless otherwise noted.)

| Parameter | Conditions | AD8091A/AD8092A | | | Unit |
|-------------------------------------|---|-----------------|--|------|------------------------------|
| | | Min | Typ | Max | |
| DYNAMIC PERFORMANCE | | | | | |
| -3 dB Small Signal Bandwidth | $G = +1$, $V_O = 0.2\text{ V p-p}$ $G = -1, +2$, $V_O = 0.2\text{ V p-p}$ | 70 | 110 50 | | MHz MHz |
| Bandwidth for 0.1 dB Flatness | $G = +2$, $V_O = 0.2\text{ V p-p}$, $R_L = 150\ \Omega$ to 2.5 V , $R_F = 402\ \Omega$ | | 17 | | MHz |
| Slew Rate | $G = -1$, $V_O = 2\text{ V Step}$ | 90 | 135 | | V/ μs |
| Full Power Response | $G = +1$, $V_O = 1\text{ V p-p}$ | | 65 | | MHz |
| Settling Time to 0.1% | $G = -1$, $V_O = 2\text{ V Step}$ | | 55 | | ns |
| NOISE/DISTORTION PERFORMANCE | | | | | |
| Total Harmonic Distortion* | $f_C = 5\text{ MHz}$, $V_O = 2\text{ V p-p}$, $G = -1$, $R_L = 100\ \Omega$ to $+1.5\text{ V}$ | | -47 | | dB |
| Input Voltage Noise | $f = 10\text{ kHz}$ | | 16 | | nV/ $\sqrt{\text{Hz}}$ |
| Input Current Noise | $f = 10\text{ kHz}$ | | 600 | | fA/ $\sqrt{\text{Hz}}$ |
| Differential Gain Error (NTSC) | $G = +2$, $V_{CM} = +1\text{ V}$ $R_L = 150\ \Omega$ to $+1.5\text{ V}$ | | 0.11 | | % |
| | $R_L = 1\text{ k}\Omega$ to $+1.5\text{ V}$ | | 0.09 | | % |
| Differential Phase Error (NTSC) | $G = +2$, $V_{CM} = +1\text{ V}$ $R_L = 150\ \Omega$ to $+1.5\text{ V}$ | | 0.24 | | Degrees |
| | $R_L = 1\text{ k}\Omega$ to $+1.5\text{ V}$ | | 0.10 | | Degrees |
| Crosstalk | $f = 5\text{ MHz}$, $G = +2$ | | -60 | | dB |
| DC PERFORMANCE | | | | | |
| Input Offset Voltage | T_{MIN} to T_{MAX} | | 1.6 | 10 | mV |
| Offset Drift | | | 10 | 25 | mV |
| Input Bias Current | T_{MIN} to T_{MAX} | | 1.3 | 2.6 | $\mu\text{A}/^\circ\text{C}$ |
| Input Offset Current | T_{MIN} to T_{MAX} | | 0.15 | 3.25 | μA |
| Open-Loop Gain | $R_L = 2\text{ k}\Omega$ | 80 | 96 | 0.8 | μA |
| | T_{MIN} to T_{MAX} | | 94 | | dB |
| | $R_L = 150\ \Omega$ | 74 | 82 | | dB |
| | T_{MIN} to T_{MAX} | | 76 | | dB |
| INPUT CHARACTERISTICS | | | | | |
| Input Resistance | | | 290 | | k Ω |
| Input Capacitance | | | 1.4 | | pF |
| Input Common-Mode Voltage Range | | | -0.2 to +2.0 | | V |
| Common-Mode Rejection Ratio | $V_{CM} = 0\text{ V}$ to 1.5 V | 72 | 88 | | dB |
| OUTPUT CHARACTERISTICS | | | | | |
| Output Voltage Swing | $R_L = 10\text{ k}\Omega$ to $+1.5\text{ V}$ $R_L = 2\text{ k}\Omega$ to $+1.5\text{ V}$ $R_L = 150\ \Omega$ to $+1.5\text{ V}$ | | 0.01 to 2.99 0.075 to 2.9 0.02 to 2.98 0.125 to 2.875 | | V V V |
| Output Current | $V_{OUT} = +0.5\text{ V}$ to $+2.5\text{ V}$ T_{MIN} to T_{MAX} | | 45 45 | | mA mA |
| Short Circuit Current | Sourcing Sinking | | 60 90 | | mA mA |
| Capacitive Load Drive | $G = +1$ | | 45 | | pF |
| POWER SUPPLY | | | | | |
| Operating Range | | 3 | | 12 | V |
| Quiescent Current/Amplifier | | | 4.2 | 4.8 | mA |
| Power Supply Rejection Ratio | $\Delta V_S = +0.5\text{ V}$ | 68 | 80 | | dB |
| OPERATING TEMPERATURE RANGE | | | | | |
| | | -40 | | +85 | $^\circ\text{C}$ |

*Refer to TPC 7.

Specifications subject to change without notice.

AD8091/AD8092—SPECIFICATIONS (@ $T_A = 25^\circ\text{C}$, $V_S = \pm 5\text{ V}$, $R_L = 2\text{ k}\Omega$ to Ground, unless otherwise noted.)

| Parameter | Conditions | AD8091A/AD8092A | | | Unit |
|-------------------------------------|--|-----------------|----------------|------|------------------------------|
| | | Min | Typ | Max | |
| DYNAMIC PERFORMANCE | | | | | |
| -3 dB Small Signal Bandwidth | $G = +1$, $V_O = 0.2\text{ V p-p}$ | 70 | 110 | | MHz |
| Bandwidth for 0.1 dB Flatness | $G = -1, +2$, $V_O = 0.2\text{ V p-p}$ | | 50 | | MHz |
| Slew Rate | $G = +2$, $V_O = 0.2\text{ V p-p}$, $R_L = 150\ \Omega$, $R_F = 1.1\text{ k}\Omega$ | | 20 | | MHz |
| Full Power Response | $G = -1$, $V_O = 2\text{ V Step}$ | 105 | 170 | | V/ μs |
| Settling Time to 0.1% | $G = +1$, $V_O = 2\text{ V p-p}$ | | 40 | | MHz |
| | $G = -1$, $V_O = 2\text{ V Step}$ | | 50 | | ns |
| NOISE/DISTORTION PERFORMANCE | | | | | |
| Total Harmonic Distortion | $f_C = 5\text{ MHz}$, $V_O = 2\text{ V p-p}$, $G = +2$ | | -71 | | dB |
| Input Voltage Noise | $f = 10\text{ kHz}$ | | 16 | | nV/ $\sqrt{\text{Hz}}$ |
| Input Current Noise | $f = 10\text{ kHz}$ | | 900 | | fA/ $\sqrt{\text{Hz}}$ |
| Differential Gain Error (NTSC) | $G = +2$, $R_L = 150\ \Omega$ | | 0.02 | | % |
| | $R_L = 1\text{ k}\Omega$ | | 0.02 | | % |
| Differential Phase Error (NTSC) | $G = +2$, $R_L = 150\ \Omega$ | | 0.11 | | Degrees |
| | $R_L = 1\text{ k}\Omega$ | | 0.02 | | Degrees |
| Crosstalk | $f = 5\text{ MHz}$, $G = +2$ | | -60 | | dB |
| DC PERFORMANCE | | | | | |
| Input Offset Voltage | | | 1.8 | 11 | mV |
| Offset Drift | T_{MIN} to T_{MAX} | | | 27 | mV |
| Input Bias Current | | | 10 | | $\mu\text{V}/^\circ\text{C}$ |
| | | | 1.4 | 2.6 | μA |
| Input Offset Current | T_{MIN} to T_{MAX} | | | 3.5 | μA |
| Open-Loop Gain | $R_L = 2\text{ k}\Omega$ | 88 | 96 | 0.75 | dB |
| | T_{MIN} to T_{MAX} | | 96 | | dB |
| | $R_L = 150\ \Omega$ | 78 | 82 | | dB |
| | T_{MIN} to T_{MAX} | | 80 | | dB |
| INPUT CHARACTERISTICS | | | | | |
| Input Resistance | | | 290 | | k Ω |
| Input Capacitance | | | 1.4 | | pF |
| Input Common-Mode Voltage Range | | | -5.2 to +4.0 | | V |
| Common-Mode Rejection Ratio | $V_{\text{CM}} = -5\text{ V to } +3.5\text{ V}$ | 72 | 88 | | dB |
| OUTPUT CHARACTERISTICS | | | | | |
| Output Voltage Swing | $R_L = 10\text{ k}\Omega$ | | -4.98 to +4.98 | | V |
| | $R_L = 2\text{ k}\Omega$ | -4.85 to +4.85 | -4.97 to +4.97 | | V |
| | $R_L = 150\ \Omega$ | -4.45 to +4.30 | -4.60 to +4.60 | | V |
| Output Current | $V_{\text{OUT}} = -4.5\text{ V to } +4.5\text{ V}$ | | 45 | | mA |
| | T_{MIN} to T_{MAX} | | 45 | | mA |
| Short Circuit Current | Sourcing | | 100 | | mA |
| | Sinking | | 160 | | mA |
| Capacitive Load Drive | $G = +1$ (AD8091/AD8092) | | 50 | | pF |
| POWER SUPPLY | | | | | |
| Operating Range | | 3 | | 12 | V |
| Quiescent Current/Amplifier | | | 4.8 | 5.5 | mA |
| Power Supply Rejection Ratio | $\Delta V_S = \pm 1\text{ V}$ | 68 | 80 | | dB |
| OPERATING TEMPERATURE RANGE | | | | | |
| | | -40 | | +85 | $^\circ\text{C}$ |

Specifications subject to change without notice.

ABSOLUTE MAXIMUM RATINGS*

| | |
|---|-----------------|
| Supply Voltage | 12.6 V |
| Power Dissipation | See Figure 1 |
| Common-Mode Input Voltage | $\pm V_S$ |
| Differential Input Voltage | ± 2.5 V |
| Output Short Circuit Duration | See Figure 1 |
| Storage Temperature Range | -65°C to +125°C |
| Operating Temperature Range | -40°C to +85°C |
| Lead Temperature Range (Soldering 10 sec) | 300°C |

*Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

MAXIMUM POWER DISSIPATION

The maximum safe power dissipation in the AD8091/AD8092 package is limited by the associated rise in junction temperature (T_J) on the die. The plastic encapsulating the die will locally reach the junction temperature. At approximately 150°C, which is the glass transition temperature, the plastic will change its properties. Even temporarily exceeding this temperature limit may change the stresses that the package exerts on the die, permanently shifting the parametric performance of the AD8091/AD8092. Exceeding a junction temperature of 175°C for an extended period of time can result in changes in the silicon devices, potentially causing failure.

The still-air thermal properties of the package (θ_{JA}), ambient temperature (T_A), and the total power dissipated in the package (P_D) can be used to determine the junction temperature of the die. The junction temperature can be calculated as follows:

$$T_J = T_A + (P_D \times \theta_{JA})$$

The power dissipated in the package (P_D) is the sum of the quiescent power dissipation and the power dissipated in the package due to the load drive for all outputs. The quiescent power is the voltage between the supply pins (V_S) times the quiescent current (I_S). Assuming the load (R_L) is referenced to midsupply, then the total drive power is $V_S/2 \times I_{OUT}$, some of which is dissipated in the package and some in the load ($V_{OUT} \times I_{OUT}$). The difference between the total drive power and the load power is the drive power dissipated in the package.

$$P_D = \text{quiescent power} + (\text{total drive power} - \text{load power})$$

$$P_D = (V_S \times I_S) + \left(\frac{V_S}{2} \times \frac{V_{OUT}}{R_L} \right) - \left(\frac{V_{OUT}^2}{R_L} \right)$$

RMS output voltages should be considered. (If R_L is referenced to $V_S/2$, as in single-supply operation, then the total drive power is $V_S \times I_{OUT}$.)

If the rms signal levels are indeterminate, then consider the worst case, when $V_{OUT} = V_S/4$ for R_L to midsupply:

$$P_D = (V_S \times I_S) + \frac{\left(\frac{V_S}{4} \right)^2}{R_L}$$

(In single-supply operation with R_L referenced to $V_S/2$, worst case is $V_{OUT} = V_S/2$.)

Airflow will increase heat dissipation, effectively reducing θ_{JA} . Also, more metal directly in contact with the package leads from metal traces, through holes, ground, and power planes will reduce the θ_{JA} . Care must be taken to minimize parasitic capacitances at the input leads of high-speed op amps as discussed in the board layout section.

Figure 1 shows the maximum safe power dissipation in the package versus the ambient temperature for the SOIC-8 (125°C/W), SOT23-5 (180°C/W), and μ SOIC-8 (150°C/W) packages on a JEDEC standard four-layer board.

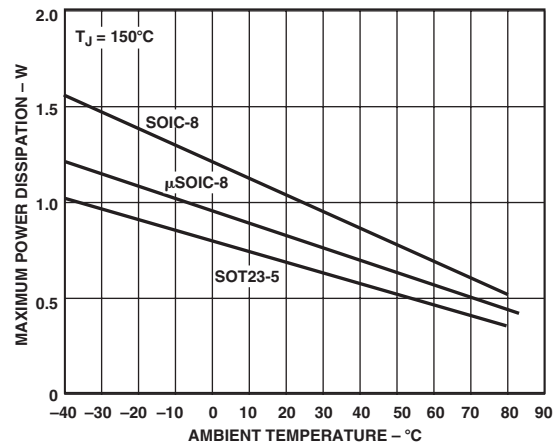


Figure 1. Maximum Power Dissipation vs. Temperature for a Four-Layer Board

AD8091/AD8092

ORDERING GUIDE

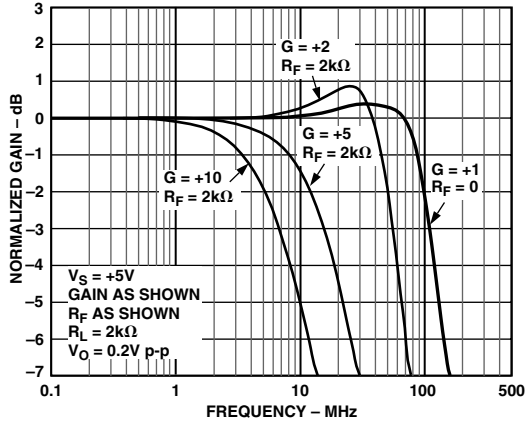
| Model | Temperature Range | Package Description | Package Outline | Branding Information |
|-----------------|-------------------|---------------------|-------------------------|----------------------|
| AD8091AR | -40°C to +85°C | 8-Lead SOIC | SO-8 | |
| AD8091AR-REEL | -40°C to +85°C | 8-Lead SOIC | 13" Tape and Reel | |
| AD8091AR-REEL7 | -40°C to +85°C | 8-Lead SOIC | 7" Tape and Reel | |
| AD8091ART-REEL | -40°C to +85°C | 5-Lead SOT-23 | RT-5, 13" Tape and Reel | HVA |
| AD8091ART-REEL7 | -40°C to +85°C | 5-Lead SOT-23 | RT-5, 7" Tape and Reel | HVA |
| AD8092AR | -40°C to +85°C | 8-Lead SOIC | SO-8 | |
| AD8092AR-REEL | -40°C to +85°C | 8-Lead SOIC | 13" Tape and Reel | |
| AD8092AR-REEL7 | -40°C to +85°C | 8-Lead SOIC | 7" Tape and Reel | |
| AD8092ARM | -40°C to +85°C | 8-Lead μ SOIC | RM-8 | HWA |
| AD8092ARM-REEL | -40°C to +85°C | 8-Lead μ SOIC | 13" Tape and Reel | HWA |
| AD8092ARM-REEL7 | -40°C to +85°C | 8-Lead μ SOIC | 7" Tape and Reel | HWA |

CAUTION

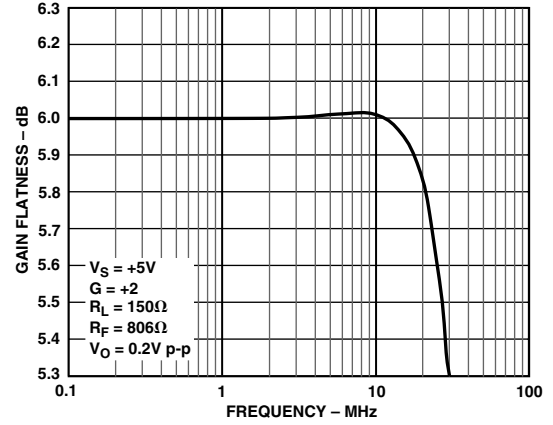
ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the AD8091/AD8092 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high-energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



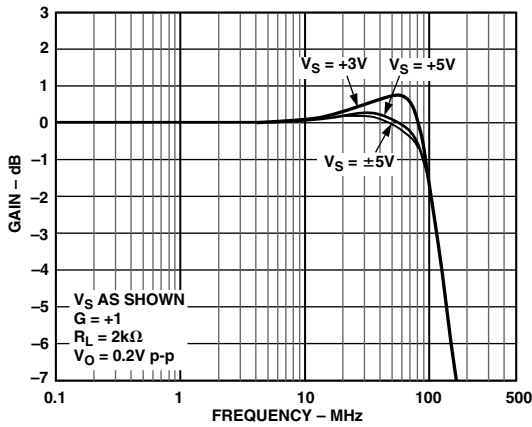
Typical Performance Characteristics—AD8091/AD8092



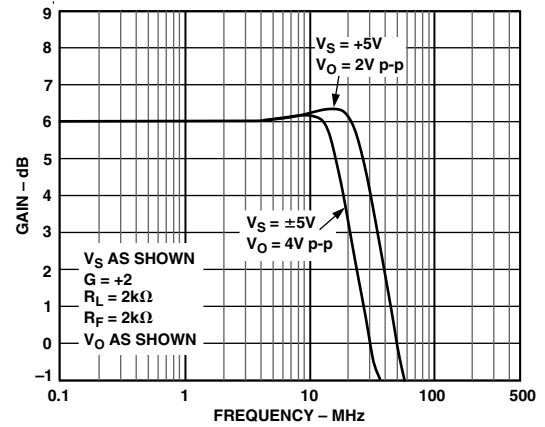
TPC 1. Normalized Gain vs. Frequency; $V_S = +5V$



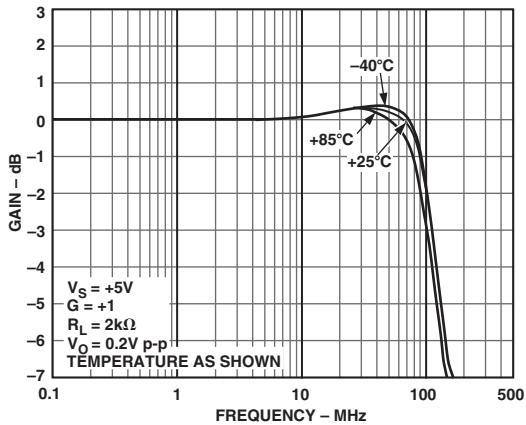
TPC 4. 0.1 dB Gain Flatness vs. Frequency; $G = +2$



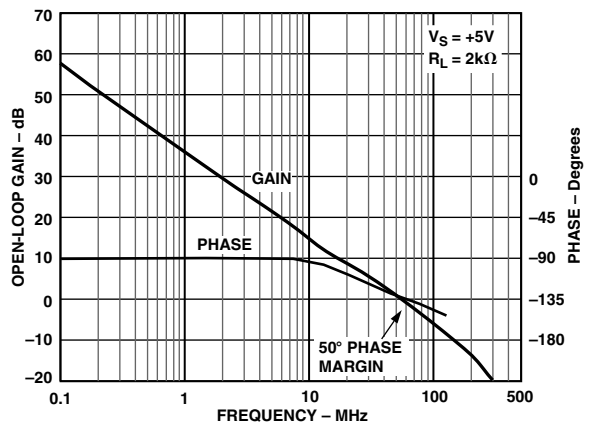
TPC 2. Gain vs. Frequency vs. Supply



TPC 5. Large Signal Frequency Response; $G = +2$

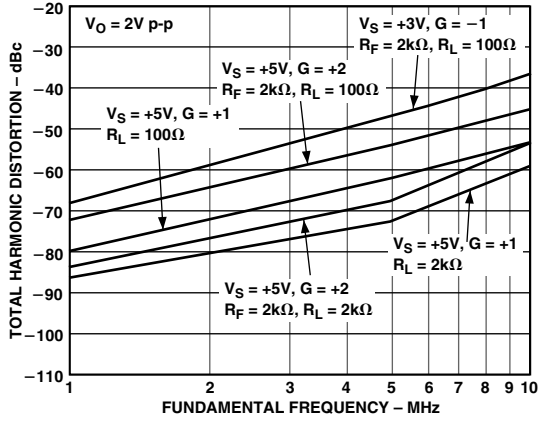


TPC 3. Gain vs. Frequency vs. Temperature

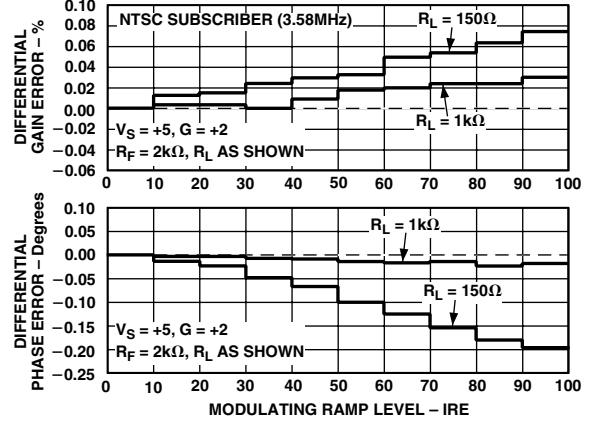


TPC 6. Open-Loop Gain and Phase vs. Frequency

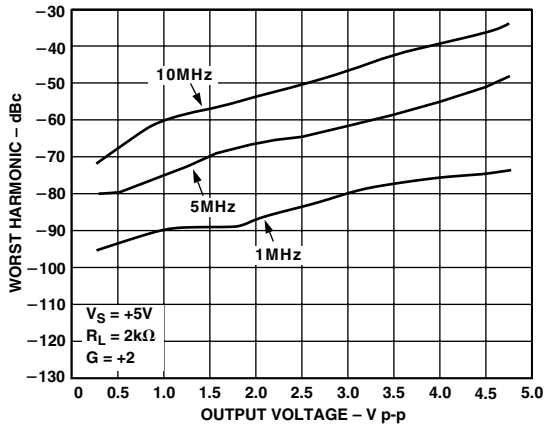
AD8091/AD8092



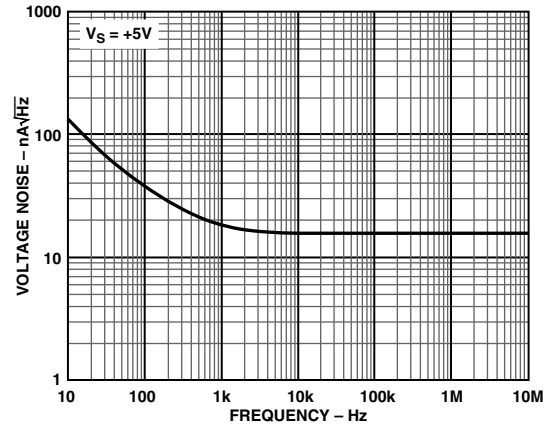
TPC 7. Total Harmonic Distortion



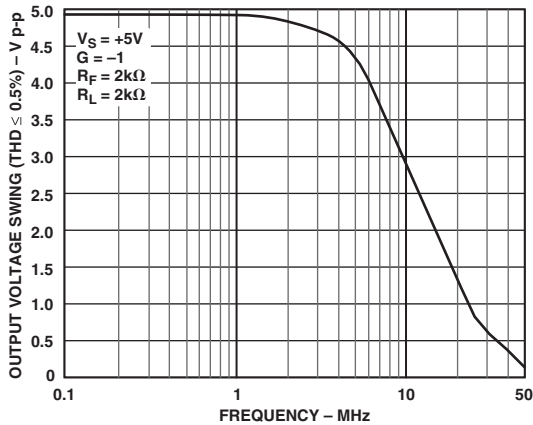
TPC 10. Differential Gain and Phase Errors



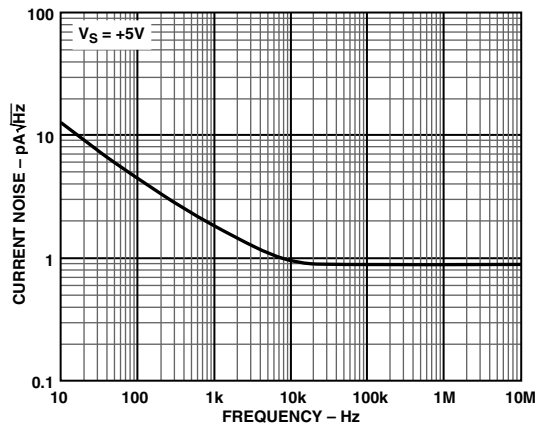
TPC 8. Worst Harmonic vs. Output Voltage



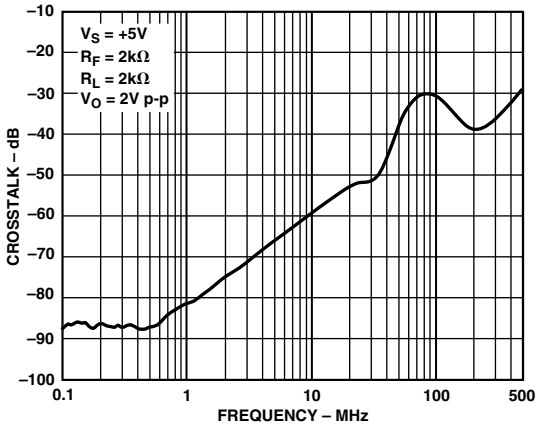
TPC 11. Input Voltage Noise vs. Frequency



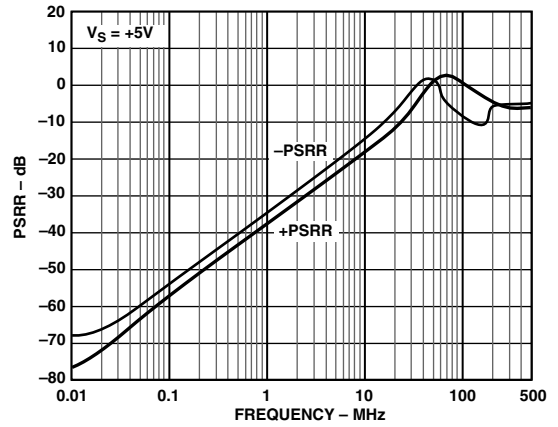
TPC 9. Low Distortion Rail-to-Rail Output Swing



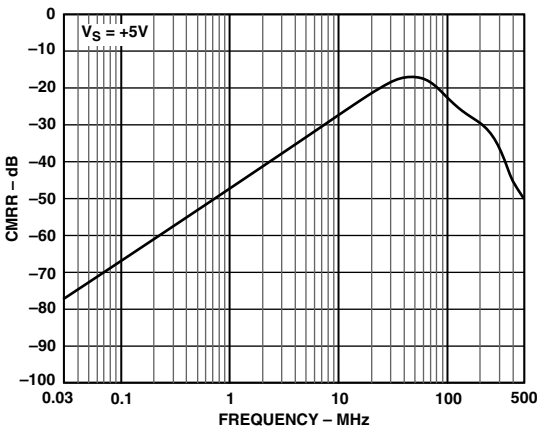
TPC 12. Input Current Noise vs. Frequency



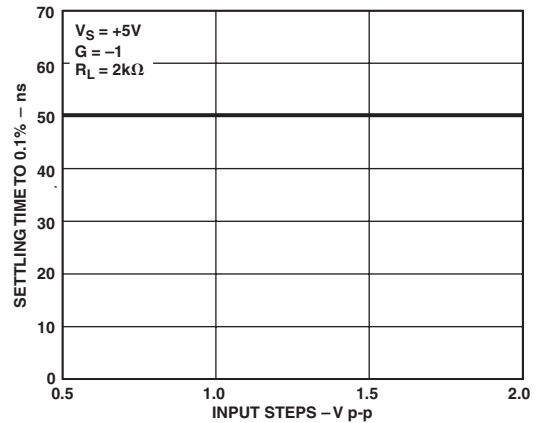
TPC 13. AD8092 Crosstalk (Output-to-Output) vs. Frequency



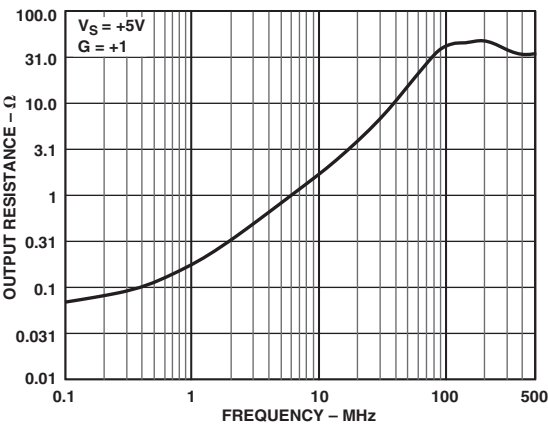
TPC 16. PSRR vs. Frequency



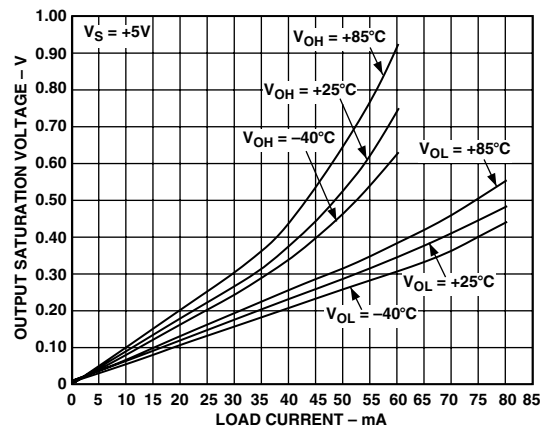
TPC 14. CMRR vs. Frequency



TPC 17. Settling Time vs. Input Step

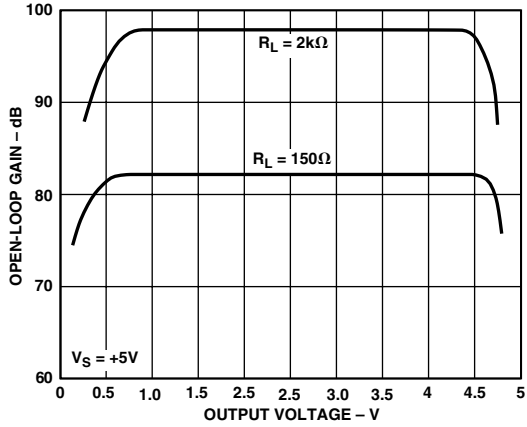


TPC 15. Closed-Loop Output Resistance vs. Frequency

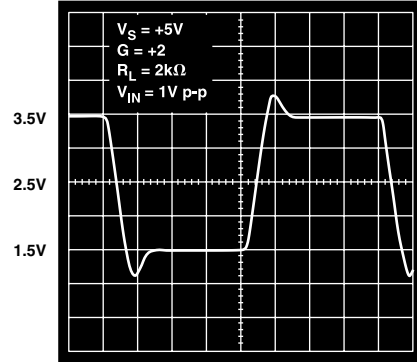


TPC 18. Output Saturation Voltage vs. Load Current

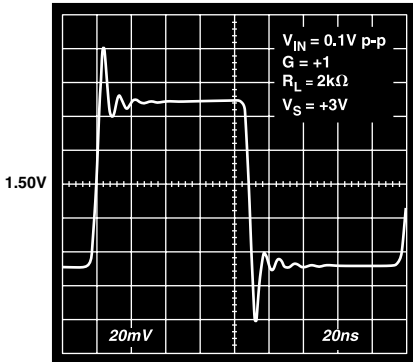
AD8091/AD8092



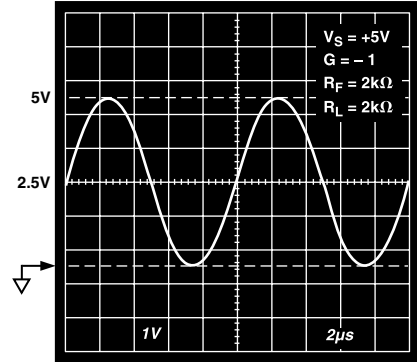
TPC 19. Open-Loop Gain vs. Output Voltage



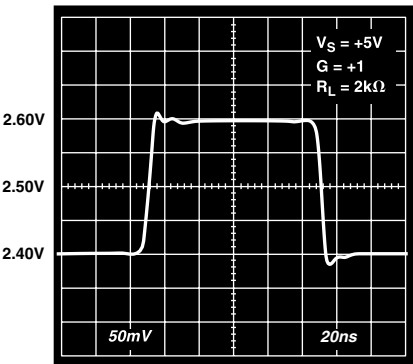
TPC 22. Large Signal Step Response; $V_S = +5\text{ V}$, $G = +2$



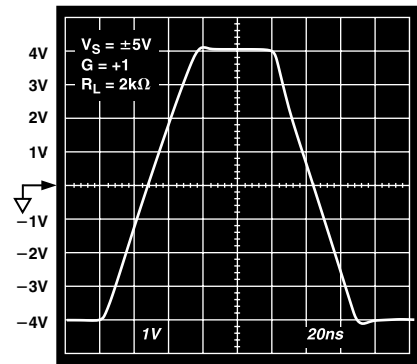
TPC 20. 100 mV Step Response; $G = +1$



TPC 23. Output Swing; $G = -1$, $R_L = 2\text{ k}\Omega$



TPC 21. 200 mV Step Response; $V_S = +5\text{ V}$, $G = +1$



TPC 24. Large Signal Step Response; $V_S = \pm 5\text{ V}$, $G = +1$

LAYOUT, GROUNDING, AND BYPASSING CONSIDERATIONS

Power Supply Bypassing

Power supply pins are actually inputs and care must be taken so that a noise-free stable dc voltage is applied. The purpose of bypass capacitors is to create low impedances from the supply to ground at all frequencies, thereby shunting or filtering a majority of the noise.

Decoupling schemes are designed to minimize the bypassing impedance at all frequencies with a parallel combination of capacitors. 0.01 μF or 0.001 μF (X7R or NPO) chip capacitors are critical and should be as close as possible to the amplifier package. Larger chip capacitors, such as the 0.1 μF capacitor, can be shared among a few closely spaced active components in the same signal path. A 10 μF tantalum capacitor is less critical for high-frequency bypassing and, in most cases, only one per board is needed at the supply inputs.

Grounding

A ground plane layer is important in densely packed PC boards to spread the current minimizing parasitic inductances. However, an understanding of where the current flows in a circuit is critical to implementing effective high-speed circuit design. The length of the current path is directly proportional to the magnitude of parasitic inductances and thus the high-frequency impedance of the path. High-speed currents in an inductive ground return will create an unwanted voltage noise.

The length of the high-frequency bypass capacitor leads are most critical. A parasitic inductance in the bypass grounding will work against the low impedance created by the bypass capacitor. Place the ground leads of the bypass capacitors at the same physical location. Because load currents flow from the supplies as well, the ground for the load impedance should be at the same physical location as the bypass capacitor grounds. For the larger value capacitors, which are intended to be effective at lower frequencies, the current return path distance is less critical.

Input Capacitance

Along with bypassing and ground, high-speed amplifiers can be sensitive to parasitic capacitance between the inputs and ground. A few pF of capacitance will reduce the input impedance at high frequencies, in turn increasing the amplifier's gain, causing peaking of the frequency response or even oscillations, if severe enough. It is recommended that the external passive components, which are connected to the input pins, be placed as close as possible to the inputs to avoid parasitic capacitance. The ground and power planes must be kept at a distance of at least 0.05 mm from the input pins on all layers of the board.

Input-to-Output Coupling

The input and output signal traces should not be parallel to minimize capacitive coupling between the inputs and output, avoiding any positive feedback.

DRIVING CAPACITIVE LOADS

A highly capacitive load will react with the output of the amplifiers, causing a loss in phase margin and subsequent peaking or even oscillation, as illustrated in Figures 2 and 3. There are two methods to effectively minimize its effect.

1. Put a small value resistor in series with the output to isolate the load capacitor from the amps' output stage.
2. Increase the phase margin with higher noise gains or by adding a pole with a parallel resistor and capacitor from $-\text{IN}$ to the output.

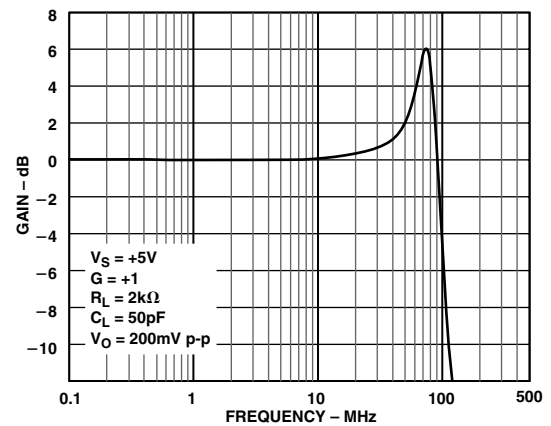


Figure 2. Closed-Loop Frequency Response: $C_L = 50 \text{ pF}$

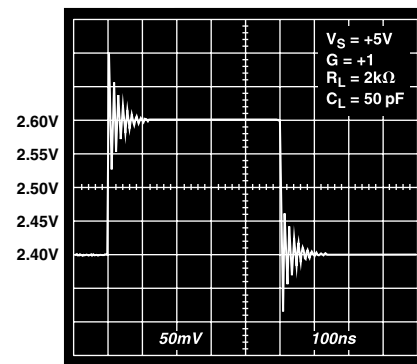


Figure 3. 200 mV Step Response: $C_L = 50 \text{ pF}$

AD8091/AD8092

As the closed-loop gain is increased, the larger phase margin allows for large capacitor loads with less peaking. Adding a low value resistor in series with the load at lower gains has the same effect. Figure 4 shows the effect of a series resistor for various voltage gains. For large capacitive loads, the frequency response of the amplifier will be dominated by the series resistor and capacitive load.

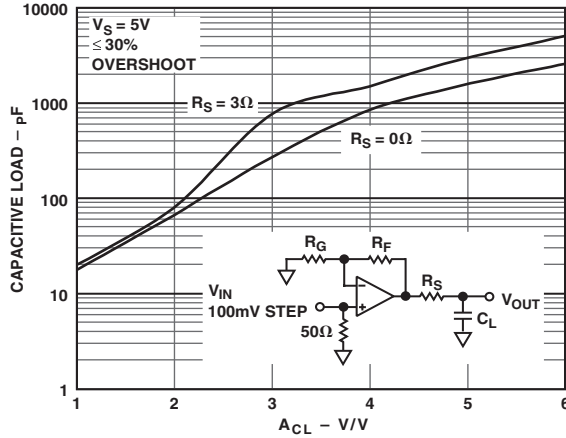


Figure 4. Capacitive Load Drive vs. Closed-Loop Gain

Overdrive Recovery

Overdrive of an amplifier occurs when the output and/or input range are exceeded. The amplifier must recover from this overdrive condition. As shown in Figure 5, the AD8091/AD8092 recovers within 60 ns from negative overdrive and within 45 ns from positive overdrive.

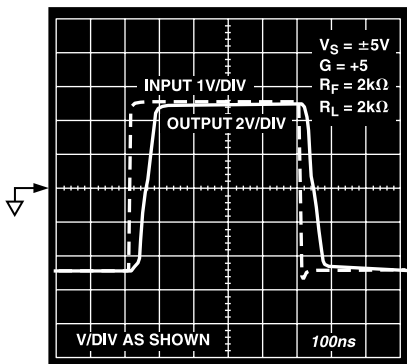


Figure 5. Overdrive Recovery

Active Filters

Active filters at higher frequencies require wider bandwidth op amps to work effectively. Excessive phase shift produced by lower frequency op amps can significantly impact active filter performance.

Figure 6 shows an example of a 2 MHz biquad bandpass filter that uses three op amps. Such circuits are sometimes used in medical ultrasound systems to lower the noise bandwidth of the analog signal before A/D conversion. Please note that the unused amplifiers' inputs should be tied to ground.

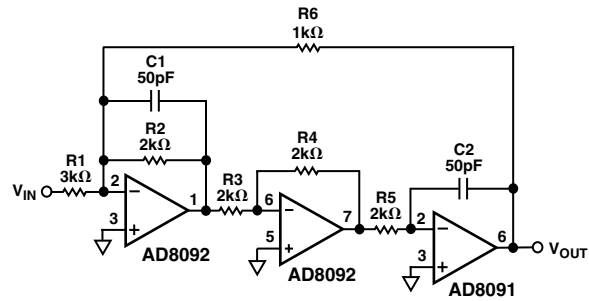


Figure 6. 2 MHz Biquad Band-Pass Filter

The frequency response of the circuit is shown in Figure 7.

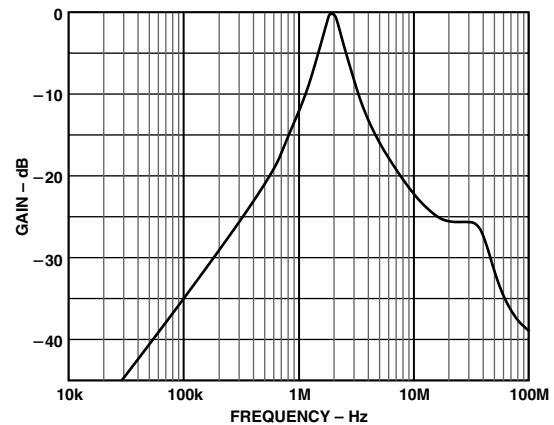


Figure 7. Frequency Response of 2 MHz Band-Pass Biquad Filter

Sync Stripper

Synchronizing pulses are sometimes carried on video signals so as not to require a separate channel to carry the synchronizing information. However, for some functions, such as A/D conversion, it is not desirable to have the sync pulses on the video signal. These

pulses will reduce the dynamic range of the video signal and do not provide any useful information for such a function.

A sync stripper will remove the synchronizing pulses from a video signal while passing all the useful video information. Figure 8 shows a practical single-supply circuit that uses only a single AD8091. It is capable of directly driving a reverse terminated video line.

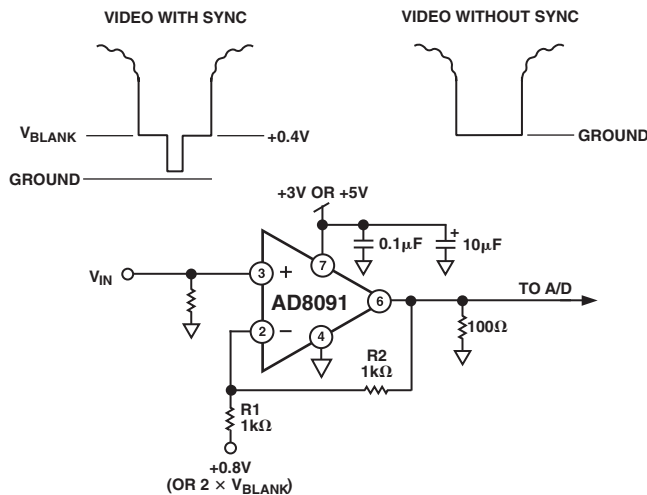


Figure 8. Sync Stripper

The video signal plus sync is applied to the noninverting input with the proper termination. The amplifier gain is set equal to 2 via the two 1 k Ω resistors in the feedback circuit. A bias voltage must be applied to R1 for the input signal to have the sync pulses stripped at the proper level.

The blanking level of the input video pulse is the desired place to remove the sync information. This level is multiplied by 2 by the amplifier. This level must be at ground at the output in order for the sync stripping action to take place. Since the gain of the amplifier from the input of R1 to the output is -1 , a voltage equal to $2 \times V_{\text{BLANK}}$ must be applied to make the blanking level come out at ground.

Single-Supply Composite Video Line Driver

Many composite video signals have their blanking level at ground and have video information that is both positive and negative. Such signals require dual-supply amplifiers to pass them. However, by ac level shifting, a single-supply amplifier can be used to pass these signals. The following complications may arise from such techniques.

Signals of bounded peak-to-peak amplitude that vary in duty cycle require larger dynamic swing capacity than their (bounded) peak-to-peak amplitude after they are ac-coupled. As a worst case, the dynamic signal swing will approach twice the peak-to-peak value. The two conditions that define the maximum dynamic swing requirements are a signal that is mostly low but goes high with a duty cycle that is a small fraction of a percent. The opposite condition defines the other extreme.

The worst case of composite video is not quite this demanding. One bounding condition is a signal that is mostly black for an entire frame but has a white (full amplitude) minimum width spike at least once in a frame.

The other extreme is a full white video signal. The blanking intervals and sync tips of such a signal will have negative-going excursions in compliance with the composite video specifications. The combination of horizontal and vertical blanking intervals limit such a signal to being at the highest (white) level for a maximum of about 75% of the time.

As a result of the duty cycles between the two extremes presented above, a 1 V p-p composite video signal that is multiplied by a gain of 2 requires about 3.2 V p-p of dynamic voltage swing at the output for an op amp to pass a composite video signal of arbitrary varying duty cycle without distortion.

Some circuits use a sync tip clamp to hold the sync tips at a relatively constant level to lower the amount of dynamic signal swing required. However, these circuits can have artifacts like sync tip compression unless they are driven by a source with a very low output impedance. The AD8091/AD8092 have adequate signal swing when running on a single +5 V supply to handle an ac-coupled composite video signal.

The input to the circuit in Figure 9 is a standard composite (1 V p-p) video signal that has the blanking level at ground. The input network level shifts the video signal by means of ac-coupling. The noninverting input of the op amp is biased to half of the supply voltage.

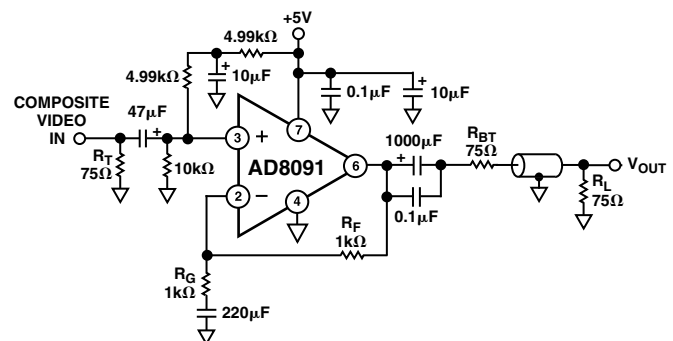


Figure 9. Single-Supply Composite Video Line Driver

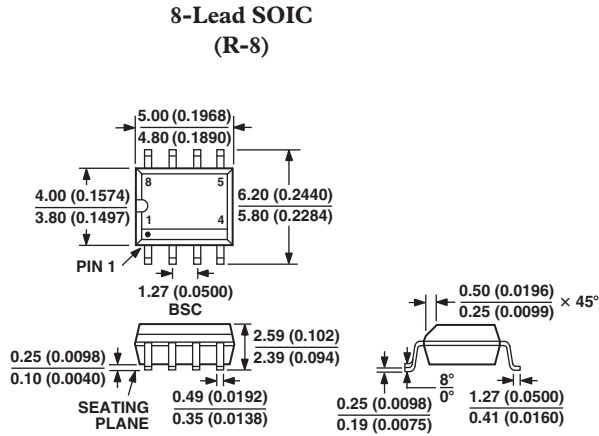
The feedback circuit provides unity gain for the dc biasing of the input and provides a gain of 2 for any signals that are in the video bandwidth. The output is ac-coupled and terminated to drive the line.

The capacitor values were selected for providing minimum “tilt” or field time distortion of the video signal. These values would be required for video that is considered to be studio or broadcast quality. However, if a lower consumer grade of video, sometimes referred to as “consumer video,” is all that is desired, the values and the cost of the capacitors can be reduced by as much as a factor of 5 with minimum visible degradation in the picture.

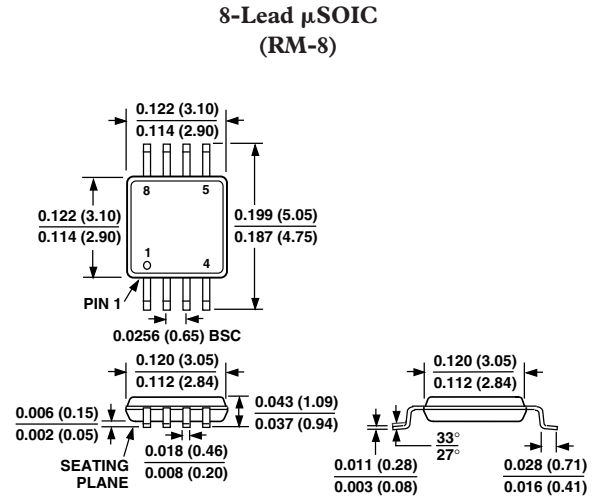
AD8091/AD8092

OUTLINE DIMENSIONS

Dimensions shown in mm and (inches)



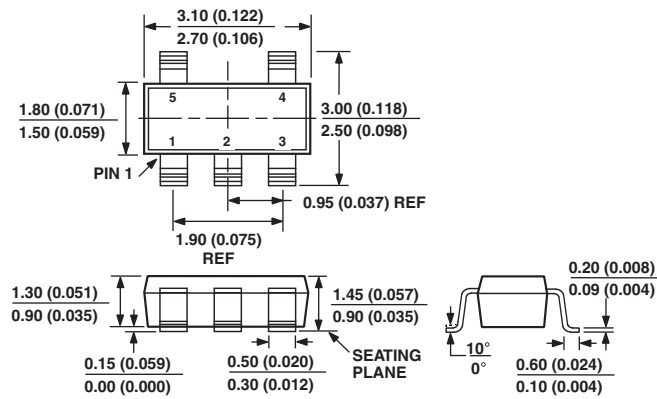
Dimensions shown in inches and (mm)



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Dimensions shown in mm and (inches)

5-Lead Plastic Surface Mount (RT-5)



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Revision History

| <u>Location</u> | <u>Page</u> |
|---|-------------|
| 5/02–Data Sheet changed from REV. 0 to REV. A. | |
| Edits to PRODUCT DESCRIPTION | 1 |
| Edit to TPC 6 | 7 |
| Edits to TPCs 21–24 | 10 |
| Edits to Figure 3 | 11 |

